MDrive®Plus MDO•34 Speed Control

Product overview

MDrive® Plus Speed Control products integrate 1.8° 2-phase stepper motor, programmable velocity control, drive electronics and optional encoder. Programmable velocity control uses voltage, current, or PWM analog input signal modes.

Product settings may be changed on-the-fly, or downloaded and stored in nonvolatile memory using the SPI Motor Interface software provided. This eliminates the need for external switches or resistors. Parameters are changed via an SPI port.

Application areas

MDrive Plus products deliver reliable performance for new and existing motion control applications. Satisfying the requirements for a wide range of machine builders.

Simplify your machine design and reduce cabinet size by replacing multiple components with a

single compact integrated motor. Fewer individual system components eliminates multiple potential failure points, and lowers risk of electrical noise by eliminating cabling between motor and drive.

These compact, powerful and cost effective motion control solutions deliver unsurpassed smoothness and performance that can reduce system cost, design and assembly time for a large range of 2-phase stepper motor applications.



MDO•34 MDrive Plus Speed Control products: integrated NEMA34 motor and controls, IP20-rated

General features

Compact integrated microstepping drive, programmable velocity control and NEMA34 1.8° 2-phase stepper motor Advanced current control for exceptional performance and smoothness +12 to +75 VDC single supply 20 microstep resolutions up to 51,200 steps per rev including: Degrees, Metric, Arc Minutes Electronically configurable Communication IP20 rating Protection 0 to +5 VDC 10 bit analog speed control input 0 to +10 VDC 4 to 20 mA 0 to 20 mA 15 to 25 kHz PWM Available options Motor stack lengths Connector options Encoders Rear control knob for manual positioning Graphical user interface provided for quick and easy parameter setup



MDO•34 Speed Control

Specifications

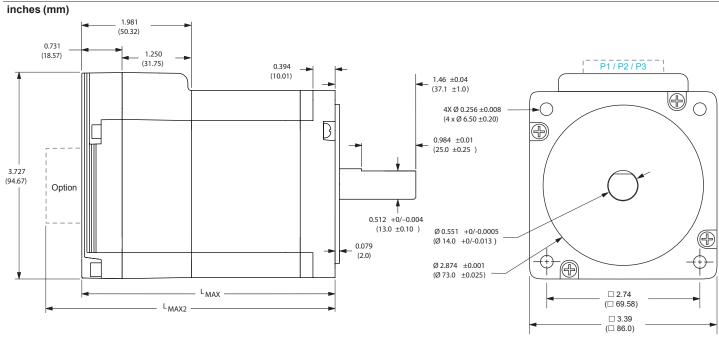
	Protocol type		SPI
Input power	Voltage	VDC	+12+75
•	Current maximum (1)	Amp	4.0
Motor	Frame size	NEMA	34
		inches	3.4
		mm	85
	Holding torque	oz-in	4081090
		N-cm	288 770
	Length	stack sizes	1, 2 & 3
Thermal	Operating temp	Heat sink maximum	75°C
	non-condensing	Motor maximum	90°C
Protection	Туре	IP rating	IP20
		Temp warning	thermal, over voltage/current
Speed control (2)	A/D resolution		10 bit
	Input		0 to +5 VDC, 0 to +10 VDC, 0-20 mA, 4-20 mA
Logic input	Low level		0 to +0.8 VDC
	High level		+2.0 to +5.0 VDC
	Internal pull-up resis- tance		20 kΩ (to +3.3 VDC)
	Optically isolated		yes
	Configurable		sinking
Logic output	Step clock/direction	Open drain source maxi- mum	+100 VDC
		Open drain current continuous	100 mA
		Output pulse width	100 nSec to 12.8 μSec software configurable
Motion	Oscillator frequency ma	ax	5 MHz
	Microstep resolution	Number of settings	20
	'	Steps per revolution	200, 400, 800, 1000, 1600, 2000, 3200, 5000, 6400, 10000, 12800, 20000, 25000, 25600, 40000, 50000, 51200, 36000 (0.01 deg/µstep), 21600 (1 arc minute/µstep), 25400 (0.001mm/µstep)
Setup parameters (2)	Function	Default setting / units	Range
	ACCL/acceleration	1,000,000 steps/sec ²	91 to 1.5 X 109
	C/joystick center (3)	0 counts	1 to 1022
	CLK OUT/clock out	none	none, step/dir, quadrature, up/down
	DB/analog deadband	1 count	0 to 255
			0.0200
		500 mSec	91 to 1.5 X 109
	DECL/deceleration DIR/motor direction	500 mSec	91 to 1.5 X 109 clockwise (cw)/counterclockwise (ccw)
	DECL/deceleration DIR/motor direction override FAULT/checksum		
	DECL/deceleration DIR/motor direction override FAULT/checksum error	none	clockwise (cw)/counterclockwise (ccw) error code
	DECL/deceleration DIR/motor direction override FAULT/checksum error FS/analog full scale HCDT/hold current	cw	clockwise (cw)/counterclockwise (ccw)
	DECL/deceleration DIR/motor direction override FAULT/checksum error FS/analog full scale HCDT/hold current delay time	none 1023 counts 500 milliseconds	clockwise (cw)/counterclockwise (ccw) error code 1 to 1023 HCDT + MSDT <= 65535
	DECL/deceleration DIR/motor direction override FAULT/checksum error FS/analog full scale HCDT/hold current	none 1023 counts 500 milliseconds 1 count	clockwise (cw)/counterclockwise (ccw) error code 1 to 1023 HCDT + MSDT <= 65535 1 to 1000
	DECL/deceleration DIR/motor direction override FAULT/checksum error FS/analog full scale HCDT/hold current delay time	none 1023 counts 500 milliseconds 1 count A1 & A2 0 to +5 VDC, volts or cur-	clockwise (cw)/counterclockwise (ccw) error code 1 to 1023 HCDT + MSDT <= 65535
	DECL/deceleration DIR/motor direction override FAULT/checksum error FS/analog full scale HCDT/hold current delay time IF/analog input filter IMODE/analog input	none 1023 counts 500 milliseconds 1 count A1 & A2	clockwise (cw)/counterclockwise (ccw) error code 1 to 1023 HCDT + MSDT <= 65535 1 to 1000 A1 spd/A2 spd or PWM 15 to 25 kHz
	DECL/deceleration DIR/motor direction override FAULT/checksum error FS/analog full scale HCDT/hold current delay time IF/analog input filter IMODE/analog input MHC/motor hold current MRC/motor run cur-	none 1023 counts 500 milliseconds 1 count A1 & A2 0 to +5 VDC, volts or current	clockwise (cw)/counterclockwise (ccw) error code 1 to 1023 HCDT + MSDT <= 65535 1 to 1000 A1 spd/A2 spd or PWM 15 to 25 kHz 0 to +5 VDC, 0 to +10 VDC, 4 to 20 mA, 0 to 20 mA
	DECL/deceleration DIR/motor direction override FAULT/checksum error FS/analog full scale HCDT/hold current delay time IF/analog input filter IMODE/analog input MHC/motor hold current MRC/motor run current MSDT/motor settling	none 1023 counts 500 milliseconds 1 count A1 & A2 0 to +5 VDC, volts or current 5 %	clockwise (cw)/counterclockwise (ccw) error code 1 to 1023 HCDT + MSDT <= 65535 1 to 1000 A1 spd/A2 spd or PWM 15 to 25 kHz 0 to +5 VDC, 0 to +10 VDC, 4 to 20 mA, 0 to 20 mA 0 to 100%
	DECL/deceleration DIR/motor direction override FAULT/checksum error FS/analog full scale HCDT/hold current delay time IF/analog input filter IMODE/analog input MHC/motor hold current MRC/motor run current	cw none 1023 counts 500 milliseconds 1 count A1 & A2 0 to +5 VDC, volts or current 5 % 25 %	clockwise (cw)/counterclockwise (ccw) error code 1 to 1023 HCDT + MSDT <= 65535 1 to 1000 A1 spd/A2 spd or PWM 15 to 25 kHz 0 to +5 VDC, 0 to +10 VDC, 4 to 20 mA, 0 to 20 mA 0 to 100% 1 to 100%
	DECL/deceleration DIR/motor direction override FAULT/checksum error FS/analog full scale HCDT/hold current delay time IF/analog input filter IMODE/analog input MHC/motor hold current MRC/motor run current MSDT/motor settling delay time MSEL/µstep resolu-	cw none 1023 counts 500 milliseconds 1 count A1 & A2 0 to +5 VDC, volts or current 5 % 25 % 0 milliseconds	clockwise (cw)/counterclockwise (ccw) error code 1 to 1023 HCDT + MSDT <= 65535 1 to 1000 A1 spd/A2 spd or PWM 15 to 25 kHz 0 to +5 VDC, 0 to +10 VDC, 4 to 20 mA, 0 to 20 mA 0 to 100% 1 to 100% MSDT + HCDT <= 65535 1, 2, 4, 5, 8, 10, 16, 25, 32, 50, 64, 100, 108, 125, 127, 128, 180, 200,
	DECL/deceleration DIR/motor direction override FAULT/checksum error FS/analog full scale HCDT/hold current delay time IF/analog input filter IMODE/analog input MHC/motor hold current MRC/motor run current MSDT/motor settling delay time MSEL/µstep resolution STEPW/step width SSD/stop/start de-	cw none 1023 counts 500 milliseconds 1 count A1 & A2 0 to +5 VDC, volts or current 5 % 25 % 0 milliseconds	clockwise (cw)/counterclockwise (ccw) error code 1 to 1023 HCDT + MSDT <= 65535 1 to 1000 A1 spd/A2 spd or PWM 15 to 25 kHz 0 to +5 VDC, 0 to +10 VDC, 4 to 20 mA, 0 to 20 mA 0 to 100% 1 to 100% MSDT + HCDT <= 65535 1, 2, 4, 5, 8, 10, 16, 25, 32, 50, 64, 100, 108, 125, 127, 128, 180, 200, 250, 256
	DECL/deceleration DIR/motor direction override FAULT/checksum error FS/analog full scale HCDT/hold current delay time IF/analog input filter IMODE/analog input MHC/motor hold current MRC/motor run current MSDT/motor settling delay time MSEL/µstep resolution STEPW/step width SSD/stop/start de- bounce	cw none 1023 counts 500 milliseconds 1 count A1 & A2 0 to +5 VDC, volts or current 5 % 25 % 0 milliseconds 256 µstep per full step 550 nSec 0 milliseconds	clockwise (cw)/counterclockwise (ccw) error code 1 to 1023 HCDT + MSDT <= 65535 1 to 1000 A1 spd/A2 spd or PWM 15 to 25 kHz 0 to +5 VDC, 0 to +10 VDC, 4 to 20 mA, 0 to 20 mA 0 to 100% 1 to 100% MSDT + HCDT <= 65535 1, 2, 4, 5, 8, 10, 16, 25, 32, 50, 64, 100, 108, 125, 127, 128, 180, 200, 250, 256 0 (square wave), 100 nSec to 12.8 µSec 0 to 255
	DECL/deceleration DIR/motor direction override FAULT/checksum error FS/analog full scale HCDT/hold current delay time IF/analog input filter IMODE/analog input MHC/motor hold current MRC/motor run current MSDT/motor settling delay time MSEL/µstep resolution STEPW/step width SSD/stop/start de- bounce VI/initial velocity	cw none 1023 counts 500 milliseconds 1 count A1 & A2 0 to +5 VDC, volts or current 5 % 25 % 0 milliseconds 256 µstep per full step 550 nSec 0 milliseconds 1000 steps/sec	clockwise (cw)/counterclockwise (ccw) error code 1 to 1023 HCDT + MSDT <= 65535 1 to 1000 A1 spd/A2 spd or PWM 15 to 25 kHz 0 to +5 VDC, 0 to +10 VDC, 4 to 20 mA, 0 to 20 mA 0 to 100% 1 to 100% MSDT + HCDT <= 65535 1, 2, 4, 5, 8, 10, 16, 25, 32, 50, 64, 100, 108, 125, 127, 128, 180, 200, 250, 256 0 (square wave), 100 nSec to 12.8 µSec 0 to 255 0 to <vm< td=""></vm<>
	DECL/deceleration DIR/motor direction override FAULT/checksum error FS/analog full scale HCDT/hold current delay time IF/analog input filter IMODE/analog input MHC/motor hold current MRC/motor run current MSDT/motor settling delay time MSEL/µstep resolution STEPW/step width SSD/stop/start de- bounce	cw none 1023 counts 500 milliseconds 1 count A1 & A2 0 to +5 VDC, volts or current 5 % 25 % 0 milliseconds 256 µstep per full step 550 nSec 0 milliseconds	clockwise (cw)/counterclockwise (ccw) error code 1 to 1023 HCDT + MSDT <= 65535 1 to 1000 A1 spd/A2 spd or PWM 15 to 25 kHz 0 to +5 VDC, 0 to +10 VDC, 4 to 20 mA, 0 to 20 mA 0 to 100% 1 to 100% MSDT + HCDT <= 65535 1, 2, 4, 5, 8, 10, 16, 25, 32, 50, 64, 100, 108, 125, 127, 128, 180, 200, 250, 256 0 (square wave), 100 nSec to 12.8 µSec 0 to 255

⁽¹⁾ Actual power supply current will depend on voltage and load.
(2) All parameters are set using the supplied SPI Motor Interface GUI and may be changed on-the-fly. An optional Communication Converter is recommended with first orders.
(3) Separate analog inputs for A1 and A2 speeds.

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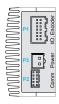
Dimensions

MDO-34 NEMA34 motor, IP20-rated



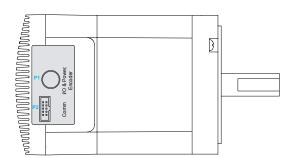
Motor stack length	Lmax	Lmax2
Single	3.81 (96.77)	4.52 (114.81)
Double	4.60 (116.84)	5.31 (134.87)
Triple	6.17 (156.72)	6.88 (174.75)

Connector options



Pluggable interface version: 14-pin* and 2-pin locking wire crimp and 10-pin friction lock wire crimp connectors

^{* 12-}pin replaced by 20-pin locking wire crimp connector when optional internal encoder is included



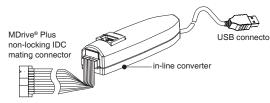
Flying leads interface version: 12" (305mm) flying leads with 10-pin non-locking IDC connector

Lmax2 option

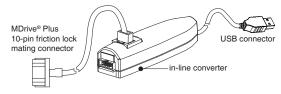


control knob

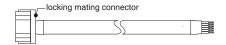
MDO•34 Speed Control



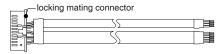
MD-CC300-001



MD-CC302-001



PD12B-2334-FL3



PD20B-3400-FL3



PD02-3400-FL3

Accessories

description	length feet (m)	part number
QuickStart Kit For rapid design verification, all-inclusive QuickStart Kits includes prototype development cables and a communication converter for MDrive Plus initial functional setup and system testing.		
For all MDrive34 Speed Control products	_	add "K" to part

Communication converter

Electrically isolated, in-line converter pre-wired with mating connector to conveniently set/program communication parameters for a single MDrive Plus via a PC's USB port.

Mates to 10-pin non-locking IDC connector	12.0 (3.6)	MD-CC300-001
Mates to 10-pin friction lock wire crimp connector	12.0 (3.6)	MD-CC302-001

Prototype development cable

Speed test/development with pre-wired mating connector with other cable end open.

Mates to 12-pin locking wire crimp connector for I/O	10.0 (3.0)	PD12B-2334-FL3
Mates to 20-pin locking wire crimp connector for I/O and internal encoder option	10.0 (3.0)	PD20B-3400-FL3
Mates to 2-pin locking wire crimp connector for power	10.0 (3.0)	PD02-3400-FL3

Mating connector kits

Connectors for assembly of cables, cable material not supplied. Sold in lots of 5. Manufacturer's crimp tool recommended for crimp connectors.

_	CK-02
_	CK-08
_	CK-11
_	CK-05
_	CK-01

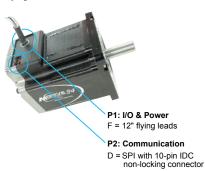
Drive protection module

Limits surge current and voltage to a safe level when DC input power is switched on-and-off to an MDrive Plus.

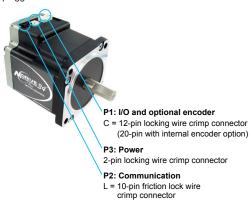
For all MDrive34 Speed Control products	_	DPM75

MDO•34 Speed Control

MDrive® 34 Plus² IP20 flying leads interface



MDrive® 34 Plus² IP20 pluggable interface



Part numbers

IP20-rated products

example part number	K	M	D	0	3	F	S	D	3	4	Α	7	-N
QuickStart Kit K = kit option, omit from part number if unwanted	K	М	D	0	3	F	S	D	3	4	Α	7	-N
MDrivePlus version MDO = Speed Control	K	M	D	0	3	F	S	D	3	4	Α	7	-N
Input 3 = Plus² version with expanded features	K	М	D	0	3	F	S	D	3	4	Α	7	-N
P1 connector F = flying leads P = pluggable	K	М	D	0	3	F	S	D	3	4	Α	7	-N
Communication type S = SPI	K	М	D	0	3	F	S	D	3	4	Α	7	-N
P2 connector D = IDC L = wire crimp	K	М	D	0	3	F	S	D	3	4	Α	7	-N
Motor size 34 = NEMA 34 3.4" / 85mm	K	М	D	0	3	F	S	D	3	4	Α	7	-N
Motor length A = single stack B = double stack C = triple stack	K	М	D	0	3	F	S	D	3	4	A	7	-N
Drive voltage 7 = +12 to +75 VDC	K	М	D	0	3	F	S	D	3	4	Α	7	-N
Options — omit from part number if unwanted -N = rear control knob for manual positioning													-N

-E__ (1) = internal optical encoder w/ index mark

line count	100	200	250	256	400	500	512	1000	1024
single-end part#	E1	E2	E3	EP	E4	E5	EQ	E6	ER
differential part #	FΔ	FR	FC	E\//	ED	ΕH	ΕY	FI	ΕV
amoronilai part n									

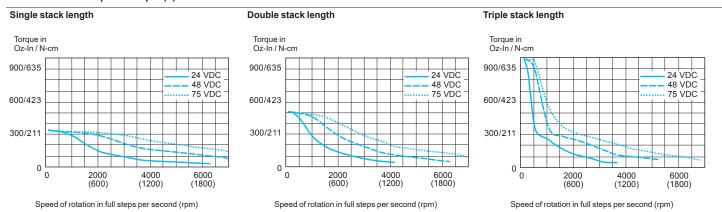
(1) Products with pluggable interface available only with differential encoder.

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Motor performance

MD•34 NEMA 34 motor specifications	Motor	or Stack length			Triple
	Haldian Assess	oz-in	408	574	1090
	Holding torque	N-cm	288	405	770
	Detent termine	oz-in	10.9	14.16	19.83
	Detent torque	N-cm	7.7	10.0	14.0
	Datas inautia	oz-in-sec ²	0.01275	0.01924	0.03849
	Rotor inertia	kg-cm ²	0.90	1.35	2.70
	Mainht (material driver)	lb	4.1	5.5	8.8
	Weight (motor+driver)	kg	1.9	2.5	4.0

MD•34 NEMA 34 speed torque (1)



(1) Test conditions: 100% current with damper simulating load.

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