## MDO•34 Speed Control

#### Product overview

MDrive® Plus Speed Control products integrate 1.8° 2-phase stepper motor, programmable velocity control, drive electronics and optional encoder. Programmable velocity control uses voltage, current, or PWM analog input signal modes.

Product settings may be changed on-the-fly, or downloaded and stored in nonvolatile memory using the SPI Motor Interface software provided. This eliminates the need for external switches or resistors. Parameters are changed via an SPI port.

#### Application areas

MDrive Plus products deliver reliable performance for new and existing motion control applications. Satisfying the requirements for a wide range of machine builders.

Simplify your machine design and reduce cabinet size by replacing multiple components with a

single compact integrated motor. Fewer individual system components eliminates multiple potential failure points, and lowers risk of electrical noise by eliminating cabling between motor and drive.

These compact, powerful and cost effective motion control solutions deliver unsurpassed smoothness and performance that can reduce system cost, design and assembly time for a large range of 2-phase stepper motor applications.



MDO•34 MDrive Plus Speed Control products: integrated NEMA34 motor and controls, IP20-rated

#### General features

Compact integrated microstepping drive, programmable velocity control and NEMA34 1.8° 2-phase stepper motor

Compact integrated interester	pping drive, programmable velocity control and NEW/104 1.0 2 phase stepper motor
Advanced current control for	exceptional performance and smoothness
+12 to +75 VDC single supply	<i>y</i>
20 microstep resolutions up to	51,200 steps per rev including: Degrees, Metric, Arc Minutes
Electronically configurable	
Communication	SPI
Protection	IP20 rating
10 bit analog speed control	0 to +5 VDC
input	0 to +10 VDC
	4 to 20 mA
	0 to 20 mA
	15 to 25 kHz PWM
Available options	Motor stack lengths
	Connector options
	Encoders
	Rear control knob for manual positioning
Graphical user interface provi	ided for quick and easy parameter setup

## MDO•34 Speed Control

### Specifications

Communication	Protocol type		SPI
Input power	Voltage	VDC	+12+75
	Current maximum (1)	Amp	4.0
Motor	Frame size	NEMA	34
		inches	3.4
		mm	85
	Holding torque	oz-in	4081090
		N-cm	288 770
	Length	stack sizes	1, 2 & 3
Thermal	Operating temp	Heat sink maximum	75°C
	non-condensing	Motor maximum	90°C
Protection	Type	IP rating	IP20
		Temp warning	thermal, over voltage/current
Speed control (2)	A/D resolution		10 bit
,	Input		0 to +5 VDC, 0 to +10 VDC, 0-20 mA, 4-20 mA
Logic input	Low level		0 to +0.8 VDC
9	High level		+2.0 to +5.0 VDC
	Internal pull-up resistance		20 kΩ (to +3.3 VDC)
	Optically isolated		yes
	Configurable		sinking
Logic output	Step clock/direction	Open drain source maximum	+100 VDC
Logic output	Step clock all ection	Open drain current continuous	100 mA
		Output pulse width	100 nSec to 12.8 μSec software configurable
Motion	Oscillator frequency max	Output puise width	5 MHz
WIGHOTT	Microstep resolution	Number of settings	20
	Wicrostep resolution	Steps per revolution	200, 400, 800, 1000, 1600, 2000, 3200, 5000, 6400, 10000, 12800, 20000,
		Steps per revolution	25000, 4000, 5000, 1000, 1000, 5000, 5000, 5000, 6400, 10000, 12500, 20000, 25000, 40000, 50000, 51200, 36000 (0.01 deg/µstep), 21600 (1 arc minute/µstep), 25400 (0.001mm/µstep)
Setup parameters (2)	Function	Default setting / units	Range
	ACCL/acceleration	1,000,000 steps/sec <sup>2</sup>	91 to 1.5 X 10 <sup>9</sup>
	C/joystick center (3)	0 counts	1 to 1022
	CLK OUT/clock out	none	none, step/dir, quadrature, up/down
	DB/analog deadband	1 count	0 to 255
	DECL/deceleration	500 mSec	91 to 1.5 X 10 <sup>9</sup>
	DIR/motor direction override	CW	clockwise (cw)/counterclockwise (ccw)
	FAULT/checksum error	none	error code
		1023 counts	
	FS/analog full scale	1023 COUITIS	1 to 1023
	FS/analog full scale HCDT/hold current delay time	500 milliseconds	1 to 1023 HCDT + MSDT <= 65535
	HCDT/hold current		
	HCDT/hold current delay time IF/analog input filter	500 milliseconds	HCDT + MSDT <= 65535
	HCDT/hold current delay time	500 milliseconds 1 count	HCDT + MSDT <= 65535 1 to 1000
	HCDT/hold current delay time IF/analog input filter IMODE/analog input	500 milliseconds  1 count A1 & A2  0 to +5 VDC, volts or current	HCDT + MSDT <= 65535 1 to 1000 A1 spd/A2 spd or PWM 15 to 25 kHz
	HCDT/hold current delay time IF/analog input filter IMODE/analog input MHC/motor hold current	500 milliseconds  1 count A1 & A2  0 to +5 VDC, volts or current	HCDT + MSDT <= 65535 1 to 1000 A1 spd/A2 spd or PWM 15 to 25 kHz 0 to +5 VDC, 0 to +10 VDC, 4 to 20 mA, 0 to 20 mA
	HCDT/hold current delay time  IF/analog input filter  IMODE/analog input  MHC/motor hold current MRC/motor run current  MSDT/motor settling	500 milliseconds  1 count A1 & A2 0 to +5 VDC, volts or current 5 %	HCDT + MSDT <= 65535  1 to 1000  A1 spd/A2 spd or PWM 15 to 25 kHz  0 to +5 VDC, 0 to +10 VDC, 4 to 20 mA, 0 to 20 mA  0 to 100%
	HCDT/hold current delay time IF/analog input filter IMODE/analog input MHC/motor hold current MRC/motor run current	500 milliseconds  1 count A1 & A2 0 to +5 VDC, volts or current 5 % 25 %	HCDT + MSDT <= 65535  1 to 1000  A1 spd /A2 spd or PWM 15 to 25 kHz  0 to +5 VDC, 0 to +10 VDC, 4 to 20 mA, 0 to 20 mA  0 to 100%  1 to 100%  MSDT + HCDT <= 65535
	HCDT/hold current delay time IF/analog input filter IMODE/analog input MHC/motor hold current MRC/motor run current MSDT/motor settling delay time	500 milliseconds  1 count A1 & A2 0 to +5 VDC, volts or current 5 % 25 % 0 milliseconds	HCDT + MSDT <= 65535  1 to 1000  A1 spd /A2 spd or PWM 15 to 25 kHz  0 to +5 VDC, 0 to +10 VDC, 4 to 20 mA, 0 to 20 mA  0 to 100%  1 to 100%  MSDT + HCDT <= 65535
	HCDT/hold current delay time  IF/analog input filter  IMODE/analog input  MHC/motor hold current  MRC/motor run current  MSDT/motor settling delay time  MSEL/µstep resolution  STEPW/step width	500 milliseconds  1 count A1 & A2 0 to +5 VDC, volts or current 5 % 25 % 0 milliseconds  256 µstep per full step 550 nSec	HCDT + MSDT <= 65535  1 to 1000  A1 spd /A2 spd or PWM 15 to 25 kHz  0 to +5 VDC, 0 to +10 VDC, 4 to 20 mA, 0 to 20 mA  0 to 100%  1 to 100%  MSDT + HCDT <= 65535  1, 2, 4, 5, 8, 10, 16, 25, 32, 50, 64, 100, 108, 125, 127, 128, 180, 200, 250, 256  0 (square wave), 100 nSec to 12.8 µSec
	HCDT/hold current delay time  IF/analog input filter  IMODE/analog input  MHC/motor hold current  MRC/motor run current  MSDT/motor settling delay time  MSEL/µstep resolution  STEPW/step width  SSD/stop/start debounce	500 milliseconds  1 count A1 & A2 0 to +5 VDC, volts or current 5 % 25 % 0 milliseconds  256 µstep per full step 550 nSec 0 milliseconds	HCDT + MSDT <= 65535  1 to 1000  A1 spd /A2 spd or PWM 15 to 25 kHz  0 to +5 VDC, 0 to +10 VDC, 4 to 20 mA, 0 to 20 mA  0 to 100%  1 to 100%  MSDT + HCDT <= 65535  1, 2, 4, 5, 8, 10, 16, 25, 32, 50, 64, 100, 108, 125, 127, 128, 180, 200, 250, 256  0 (square wave), 100 nSec to 12.8 μSec  0 to 255
	HCDT/hold current delay time  IF/analog input filter  IMODE/analog input  MHC/motor hold current  MRC/motor run current  MSDT/motor settling delay time  MSEL/µstep resolution  STEPW/step width  SSD/stop/start debounce  VI/initial velocity	500 milliseconds  1 count A1 & A2 0 to +5 VDC, volts or current 5 % 25 % 0 milliseconds  256 µstep per full step 550 nSec 0 milliseconds  1000 steps/sec	HCDT + MSDT <= 65535  1 to 1000 A1 spd/A2 spd or PWM 15 to 25 kHz 0 to +5 VDC, 0 to +10 VDC, 4 to 20 mA, 0 to 20 mA 0 to 100% 1 to 100% MSDT + HCDT <= 65535 1, 2, 4, 5, 8, 10, 16, 25, 32, 50, 64, 100, 108, 125, 127, 128, 180, 200, 250, 256 0 (square wave), 100 nSec to 12.8 μSec 0 to 255 0 to <vm< td=""></vm<>
	HCDT/hold current delay time  IF/analog input filter  IMODE/analog input  MHC/motor hold current  MRC/motor run current  MSDT/motor settling delay time  MSEL/µstep resolution  STEPW/step width  SSD/stop/start debounce	500 milliseconds  1 count A1 & A2 0 to +5 VDC, volts or current 5 % 25 % 0 milliseconds  256 µstep per full step 550 nSec 0 milliseconds	HCDT + MSDT <= 65535  1 to 1000 A1 spd/A2 spd or PWM 15 to 25 kHz 0 to +5 VDC, 0 to +10 VDC, 4 to 20 mA, 0 to 20 mA 0 to 100% 1 to 100% MSDT + HCDT <= 65535 1, 2, 4, 5, 8, 10, 16, 25, 32, 50, 64, 100, 108, 125, 127, 128, 180, 200, 250, 256 0 (square wave), 100 nSec to 12.8 μSec 0 to 255

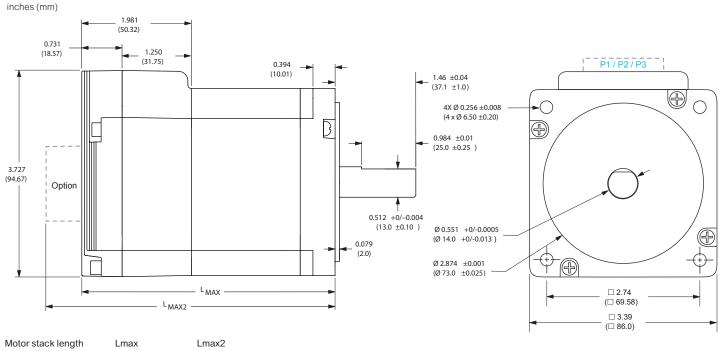
<sup>(1)</sup> Actual power supply current will depend on voltage and load.
(2) All parameters are set using the supplied SPI Motor Interface GUI and may be changed on-the-fly. An optional Communication Converter is recommended with first orders.

<sup>(3)</sup> Separate analog inputs for A1 and A2 speeds.

## MDO•34 Speed Control

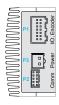
#### **Dimensions**

### MDO•34 NEMA34 motor, IP20-rated



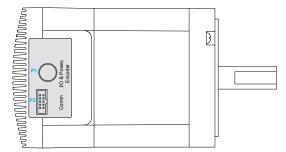
Motor stack length	Lmax	Lmax2
Single	3.81 (96.77)	4.52 (114.81)
Double	4.60 (116.84)	5.31 (134.87)
Triple	6.17 (156.72)	6.88 (174.75)

#### Connector options



Pluggable interface version: 14-pin\* and 2-pin locking wire crimp and 10-pin friction lock wire crimp connectors

<sup>\* 12-</sup>pin replaced by 20-pin locking wire crimp connector when optional internal encoder is included



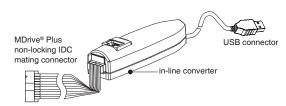
Flying leads interface version: 12" (305mm) flying leads with 10-pin non-locking IDC connector Lmax2 option



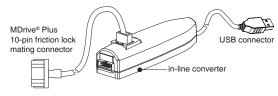
control knob

www.motion.schneider-electric.com

### MDO•34 Speed Control



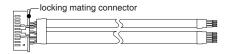
MD-CC300-001



MD-CC302-001



PD12B-2334-FL3



PD20B-3400-FL3



PD02-3400-FL3

#### Accessories

description	length feet (m)	part number

#### QuickStart Kit

For rapid design verification, all-inclusive QuickStart Kits includes prototype development cables and a communication converter for MDrive Plus initial functional setup and system testing.

For all MDrive34 Speed Control products	_	add "K" to part number
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#### Communication converter

Electrically isolated, in-line converter pre-wired with mating connector to conveniently set/program communication parameters for a single MDrive Plus via a PC's USB port.

Mates to 10-pin non-locking IDC connector	12.0 (3.6)	MD-CC300-001
Mates to 10-pin friction lock wire crimp connector	12.0 (3.6)	MD-CC302-001

#### Prototype development cable

Speed test/development with pre-wired mating connector with other cable end open.

Mates to 12-pin locking wire crimp connector for I/O	10.0 (3.0)	PD12B-2334-FL3
Mates to 20-pin locking wire crimp connector for I/O and internal encoder option	10.0 (3.0)	PD20B-3400-FL3
Mates to 2-pin locking wire crimp connector for power	10.0 (3.0)	PD02-2300-FL3

#### Mating connector kits

Connectors for assembly of cables, cable material not supplied. Sold in lots of 5. Manufacturer's crimp tool recommended for crimp connectors.

10-pin friction lock wire crimp connector for communication	_	CK-02
12-pin locking wire crimp connector for I/O	_	CK-08
20-pin locking wire crimp connector for I/O and internal encoder option	_	CK-11
2-pin locking wire crimp connector for power	_	CK-05
10-pin non-locking IDC connector for communication	_	CK-01

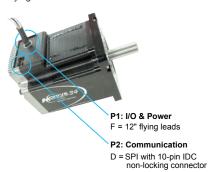
#### Drive protection module

Limits surge current and voltage to a safe level when DC input power is switched on-and-off to an MDrive Plus.

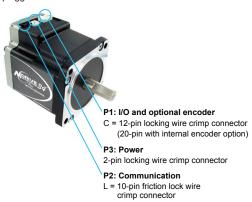
For all MDrive34 Speed Control products	_	DPM75

## MDO•34 Speed Control

MDrive® 34 Plus² IP20 flying leads interface



MDrive® 34 Plus² IP20 pluggable interface



#### Part numbers

### IP20-rated products

example part number	K	M	D	0	3	F	S	D	3	4	Α	7	-N
QuickStart Kit K = kit option, omit from part number if unwanted	K	М	D	0	3	F	S	D	3	4	Α	7	-N
MDrivePlus version MDO = Speed Control	Κ	M	D	0	3	F	S	D	3	4	Α	7	-N
Input 3 = Plus² version with expanded features	K	М	D	0	3	F	S	D	3	4	Α	7	-N
P1 connector F = flying leads P = pluggable	K	М	D	0	3	F	S	D	3	4	Α	7	-N
Communication type S = SPI	K	М	D	0	3	F	S	D	3	4	Α	7	-N
P2 connector D = IDC L = wire crimp	K	М	D	0	3	F	S	D	3	4	Α	7	-N
Motor size 34 = NEMA 34 3.4"/85mm	K	М	D	0	3	F	S	D	3	4	А	7	-N
Motor length A = single stack B = double stack C = triple stack	K	М	D	0	3	F	S	D	3	4	Α	7	-N
Drive voltage 7 = +12 to +75 VDC	K	М	D	0	3	F	S	D	3	4	Α	7	-N
Options — omit from part number if unwanted													-N
-N = rear control knob for manual positioning -E(1) = internal optical encoder w/ index mark    line count	E	00 6 J	E	)24 R Y									

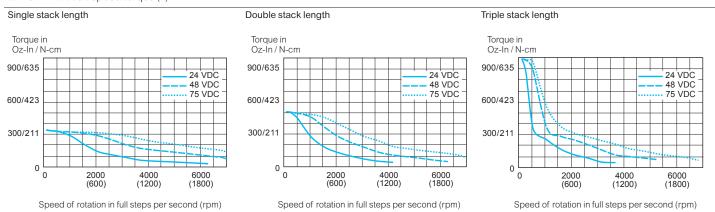
(1) Products with pluggable interface available only with differential encoder.

### MDO•34 Speed Control

### Motor performance

MD•34 NEMA 34 motor specifications	Motor	Stack length	Single	Double	Triple
	Holding torque	oz-in	408	574	1090
	Holding torque	N-cm	288	405	770
	Detent torque	oz-in	10.9	14.16	19.83
	Detent torque	N-cm	7.7	10.0	14.0
	Rotor inertia	oz-in-sec²	0.01275	0.01924	0.03849
	Rotor mertia	kg-cm <sup>2</sup>	0.90	1.35	2.70
	Weight (motor+driver)	lb	4.1	5.5	8.8
	weight (motor-driver)	kg	1.9	2.5	4.0

#### MD•34 NEMA 34 speed torque (1)



(1) Test conditions: 100% current with damper simulating load.

Intelligent motion systems Schneider